

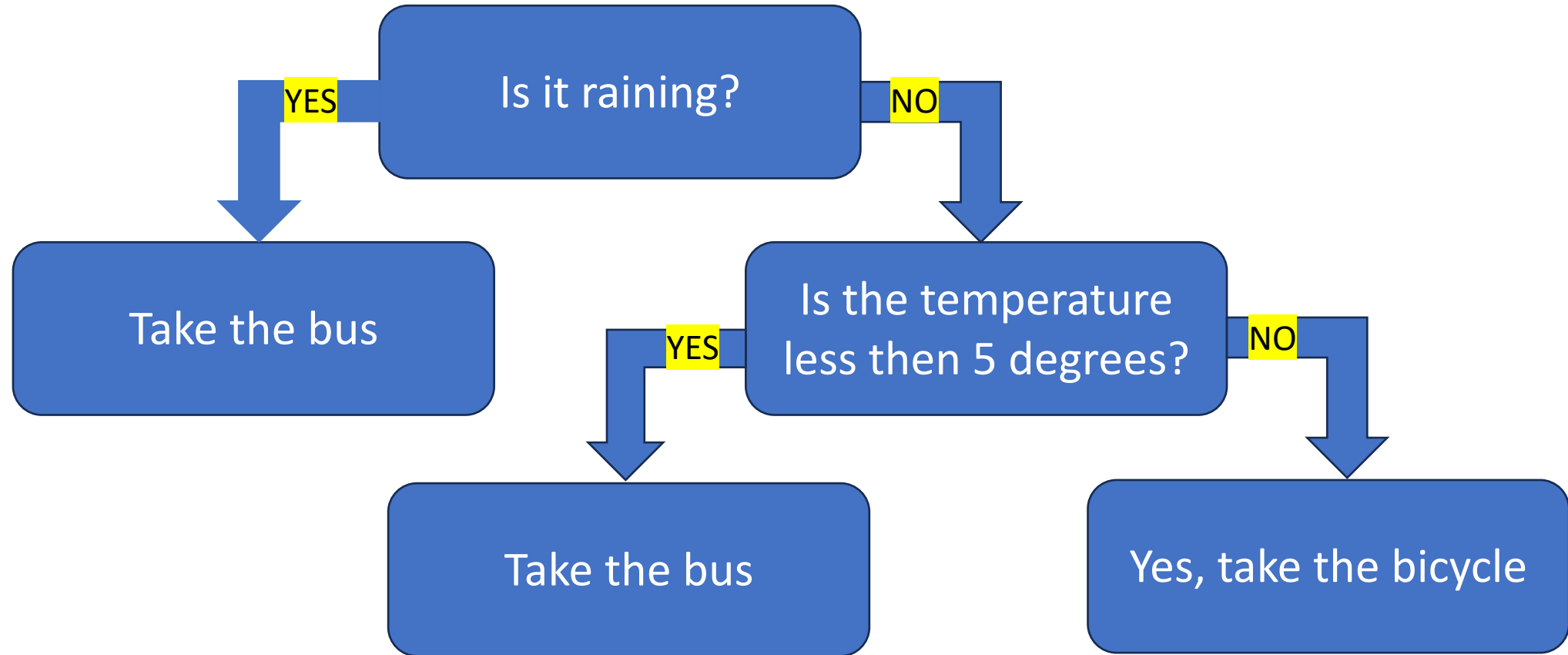
Lecture 7: Tree Based Methods

Applied Data Analysis and Visualization

Anastasia Giachanou, Ayoub Bagheri

What	When
Linear regression for data science	Week 4
Classification	Week 5
Interactive visualizations with R shiny	Week 6
Tree-based methods	Week 7
Introduction to text mining	Week 8
Network analysis	Week 9
EXAM	Week 10

Should I bike to the Univeristy?



Main points for today

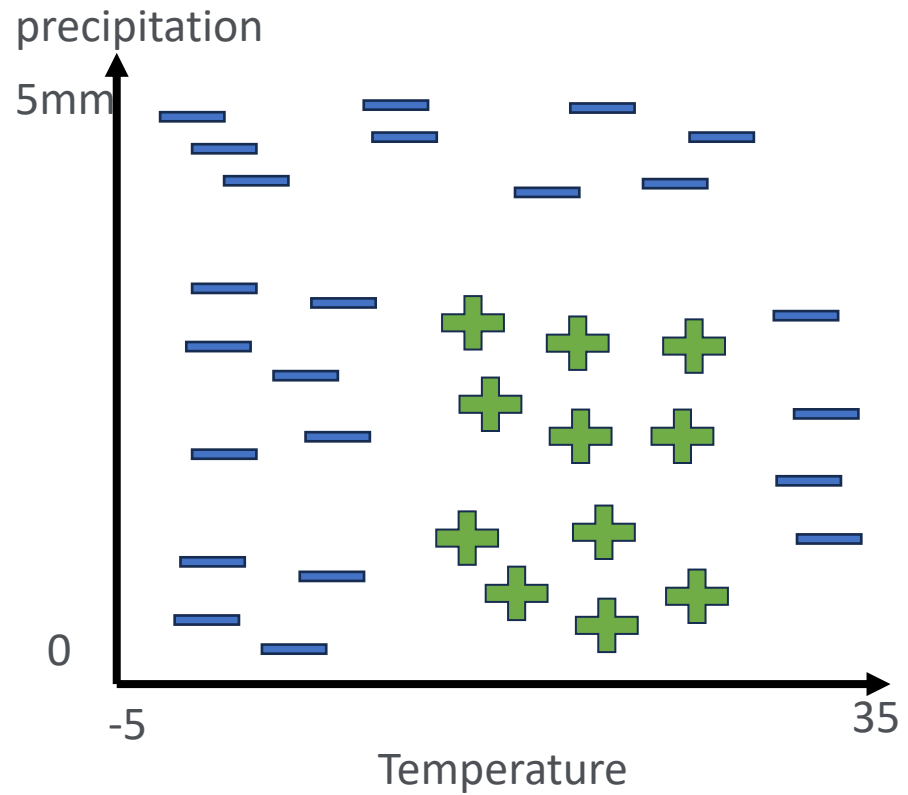
- Tree-based methods: segment predictor space into a number of simple regions
- Using decision trees for prediction
- Improvement 1: Bagging
- Improvement 2: Random forests
- Approximate the test error using the Out of Bag (OOB) error
- Variable importance measures
- Conclusions



Decision Trees

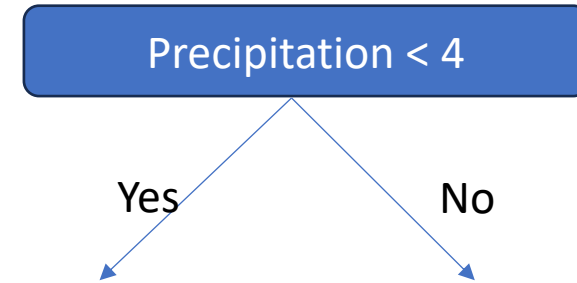
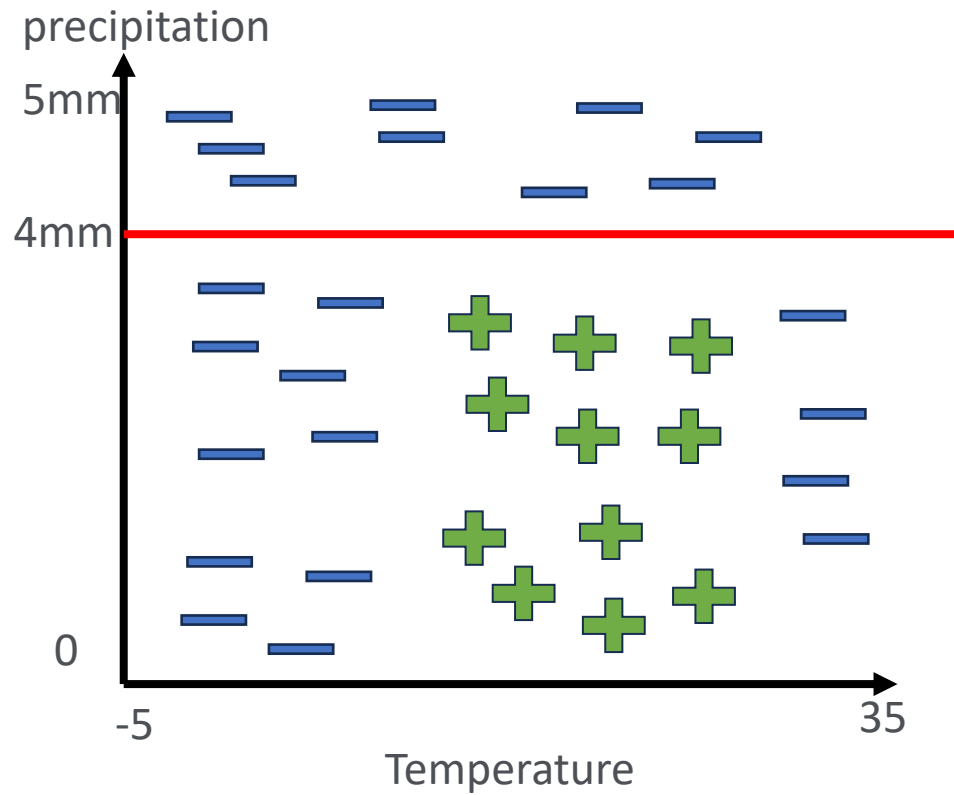
Basics of Decision Trees

- Shall we go to a picnic?



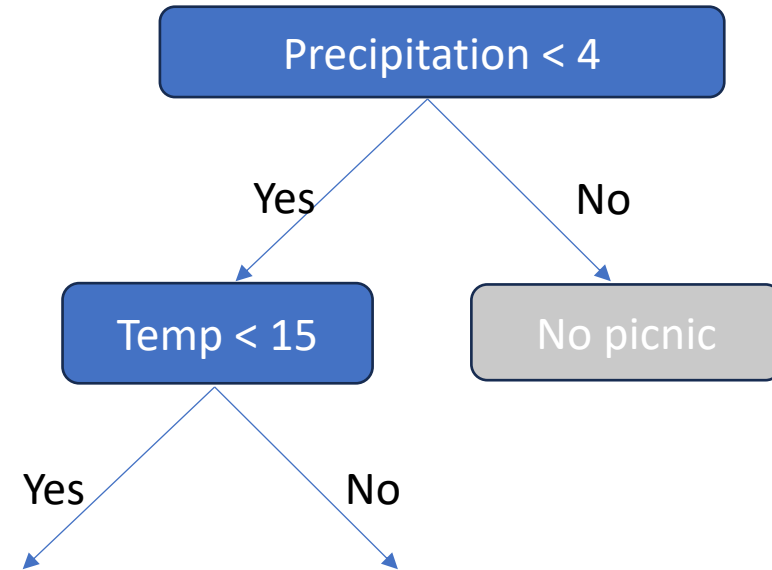
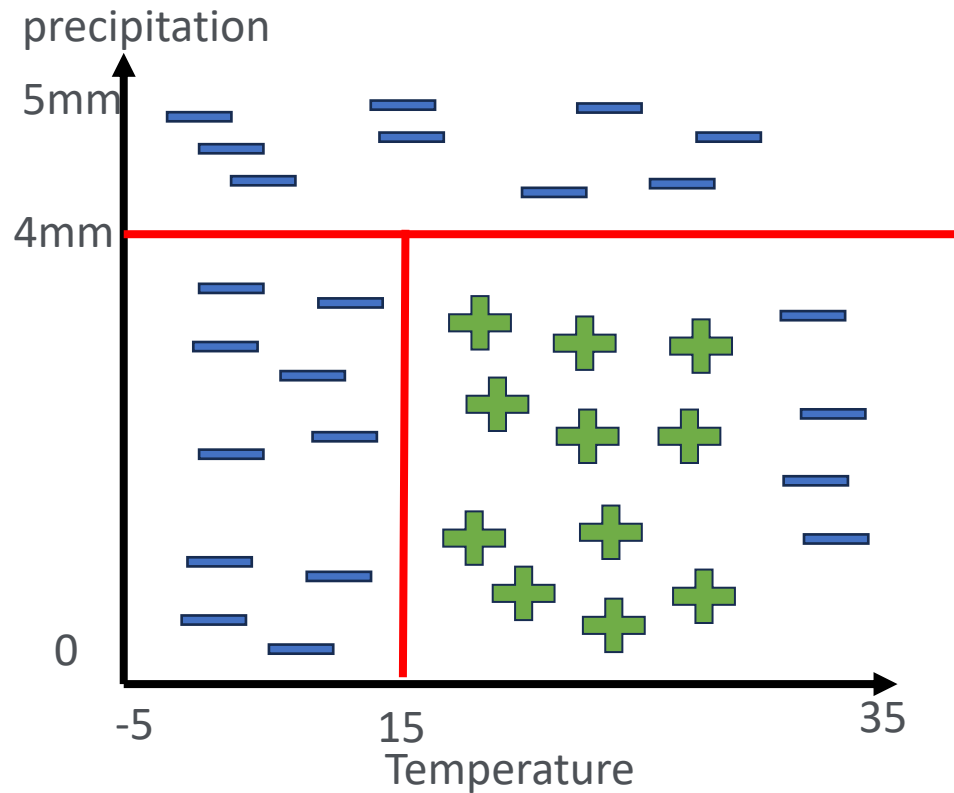
Basics of Decision Trees

- Shall we go to a picnic?



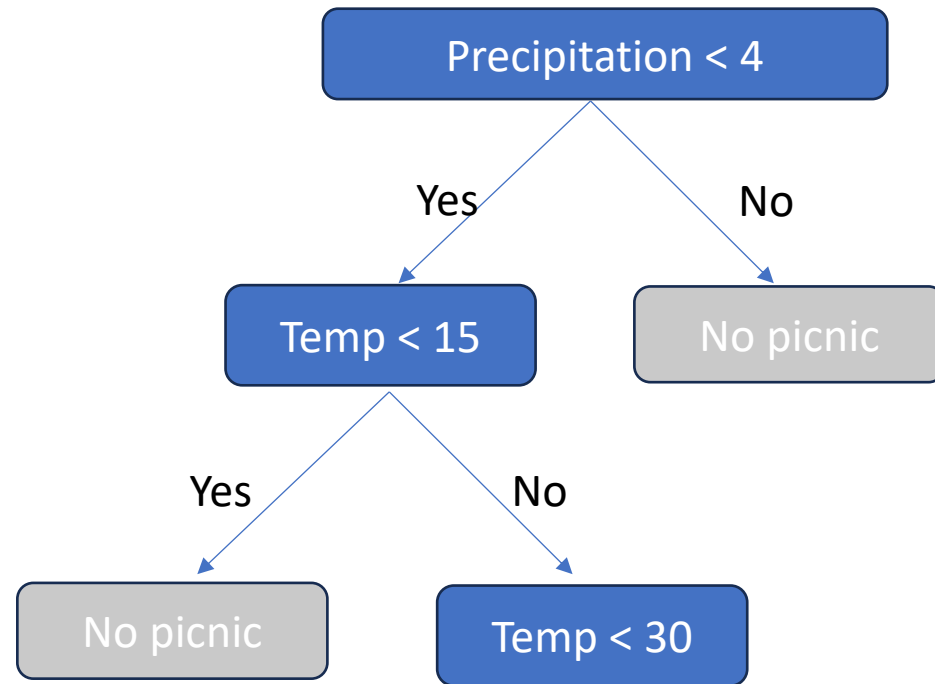
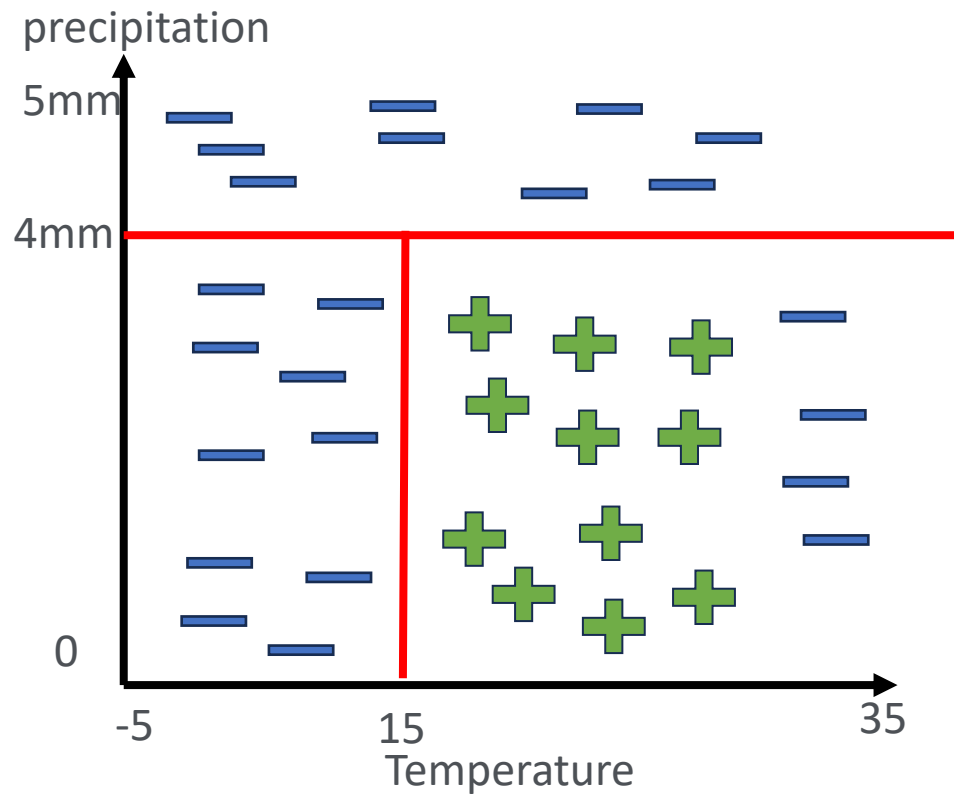
Basics of Decision Trees

- Shall we go to a picnic?



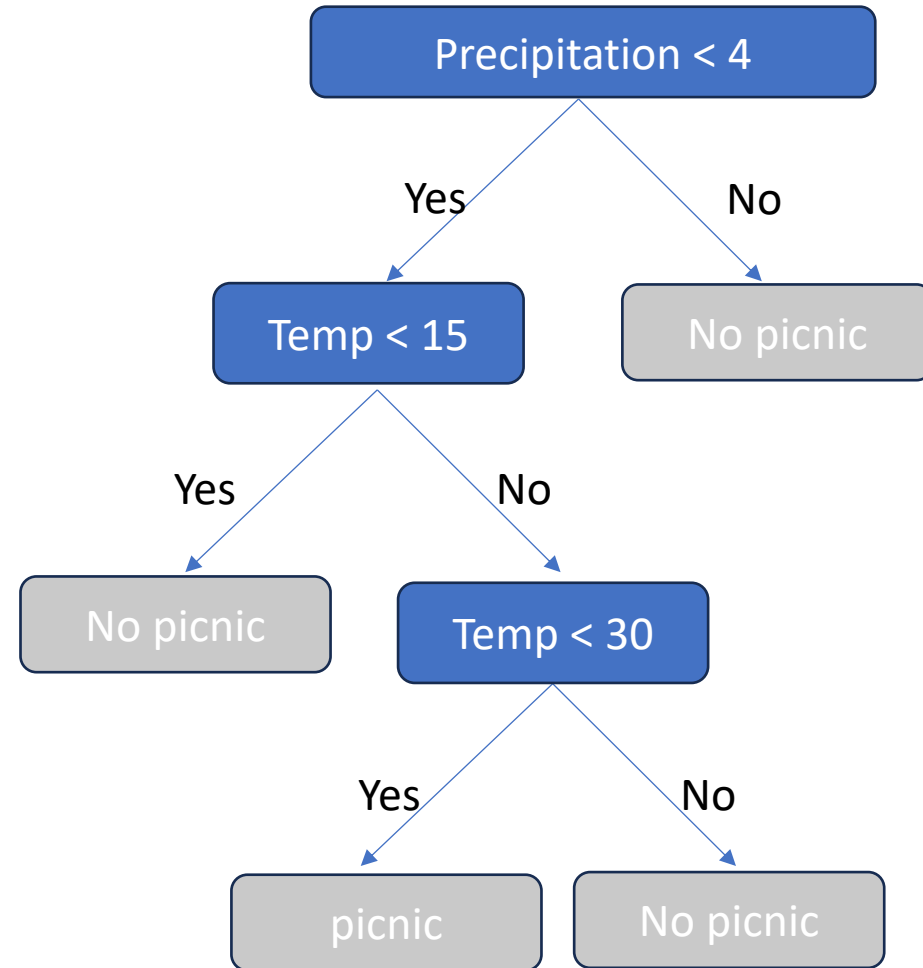
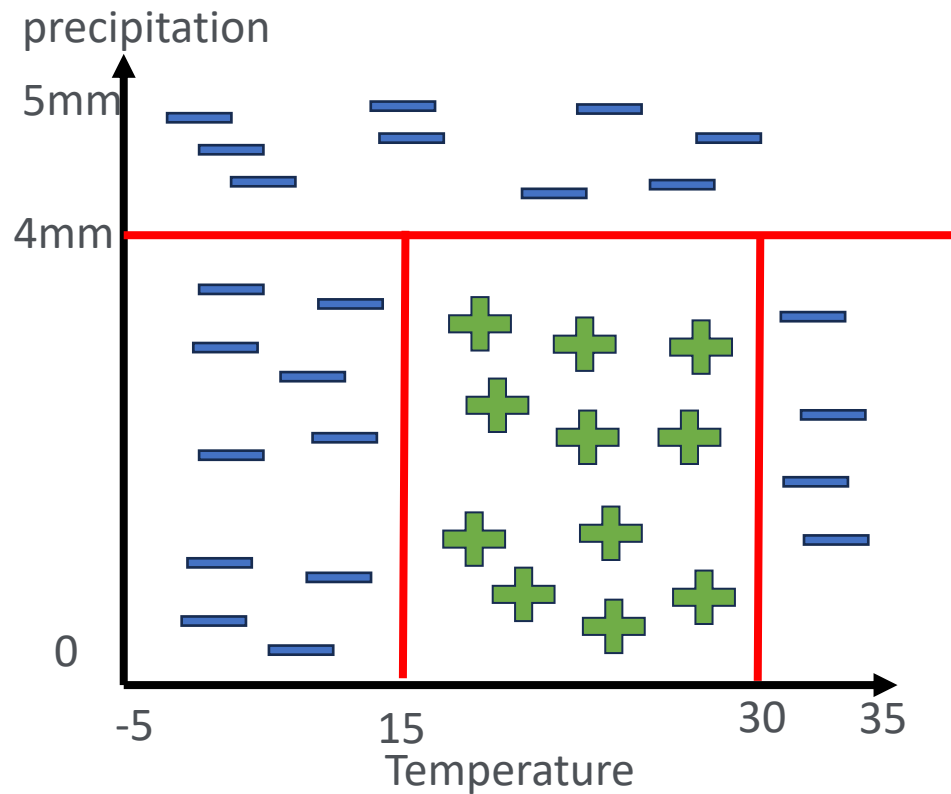
Basics of Decision Trees

- Shall we go to a picnic?

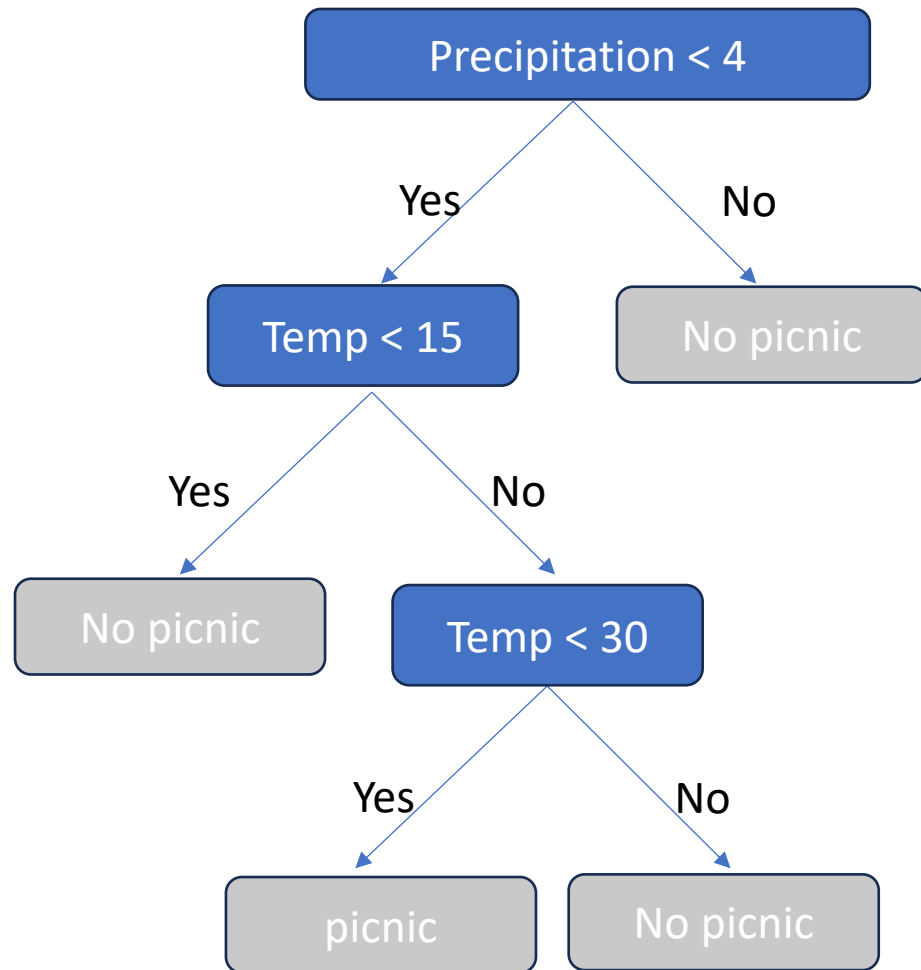


Basics of Decision Trees

- Shall we go to a picnic?



Basics of Decision Trees



Features:

x1: precipitation

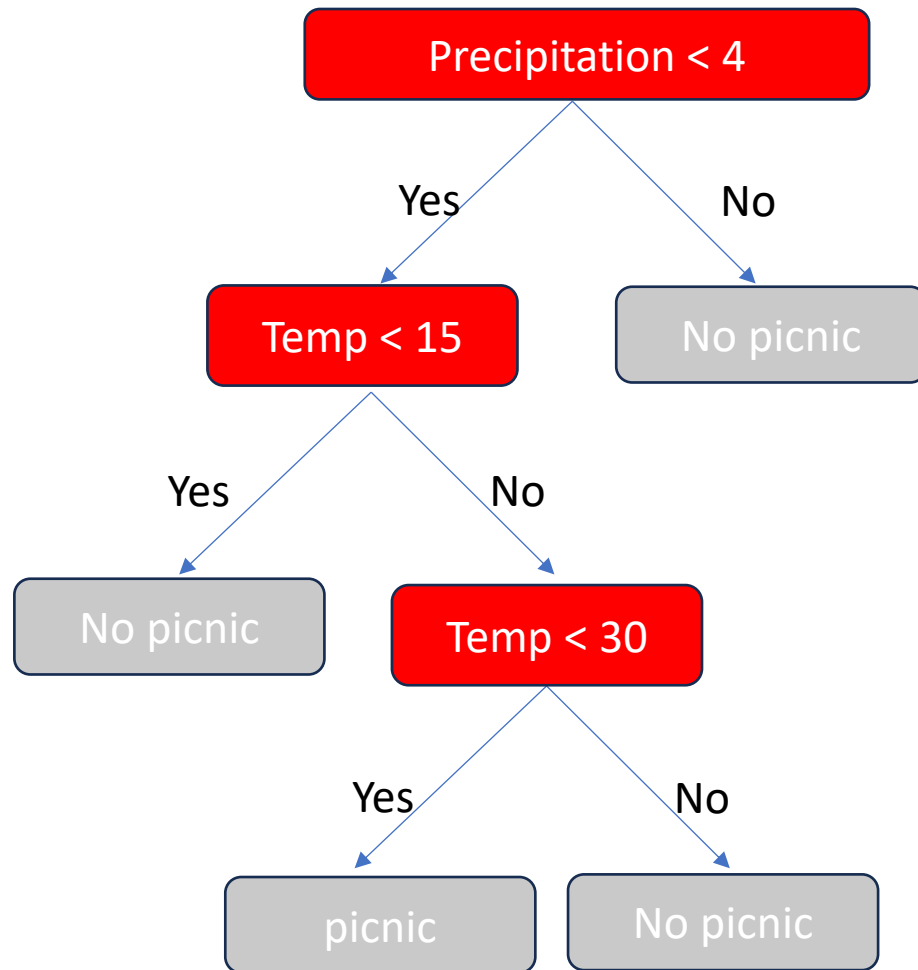
x2: temperature

labels y:

1: picnic

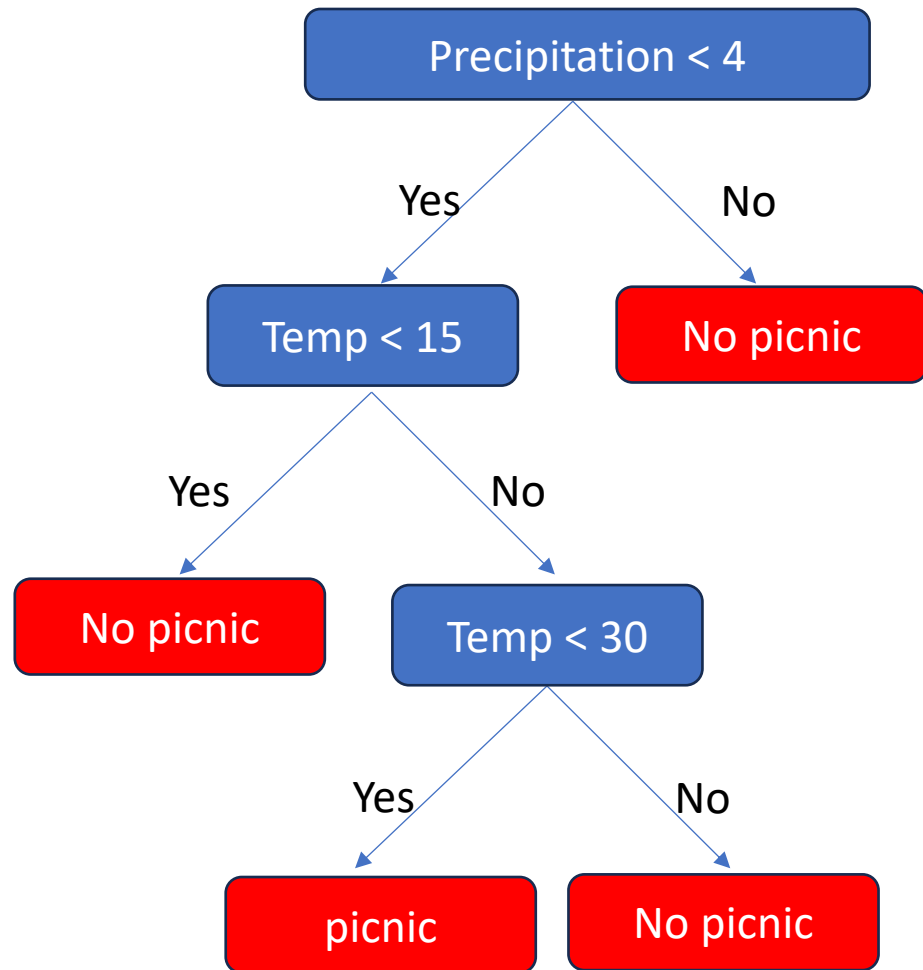
0: no picnic

Basics of Decision Trees



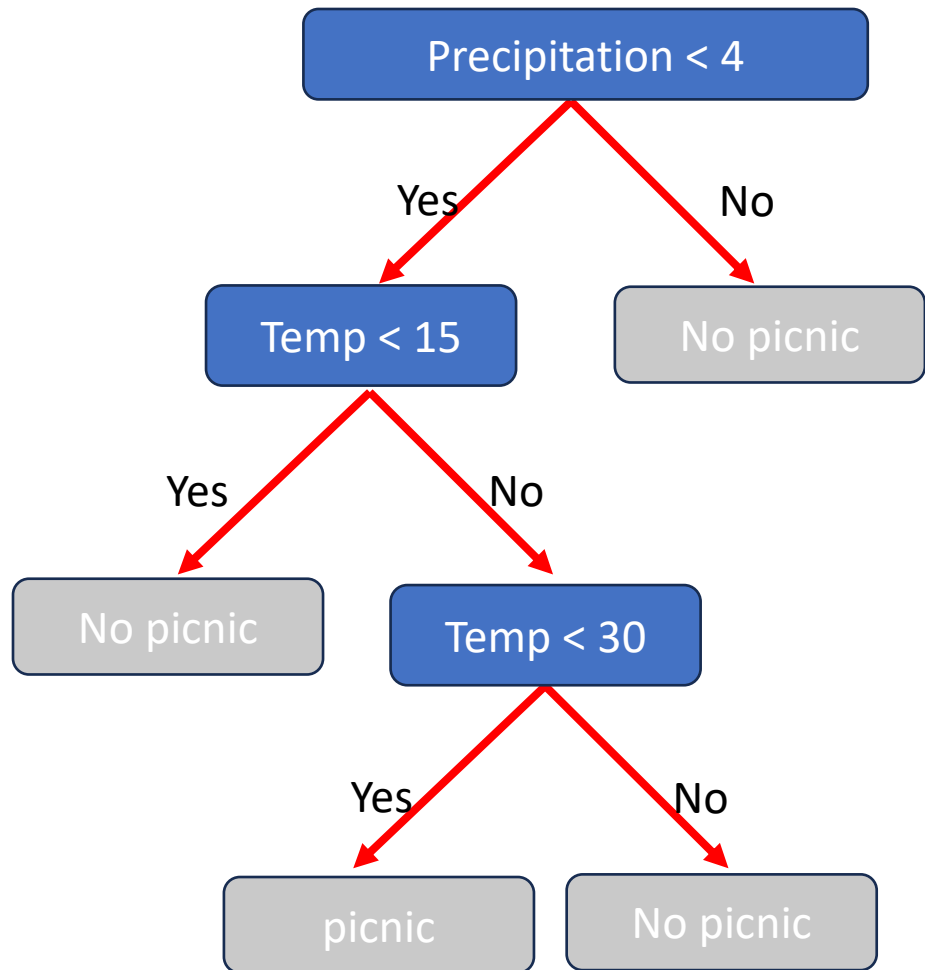
- Internal nodes
- Two children that can be:
 - internal node

Basics of Decision Trees



- Internal nodes
- Two children that can be:
 - internal node
 - leaves or terminal node

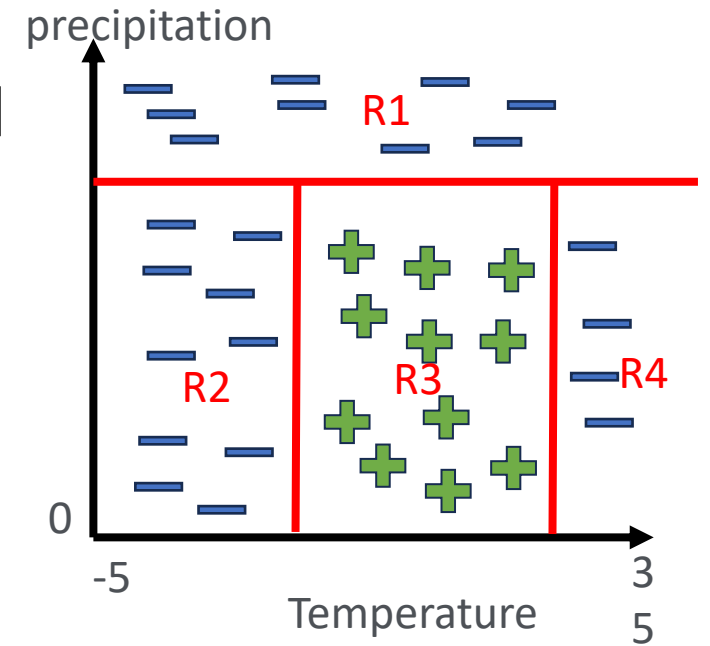
Basics of Decision Trees



- Internal nodes
- Two children that can be:
 - internal node
 - leaves or terminal node
- Connections with branches

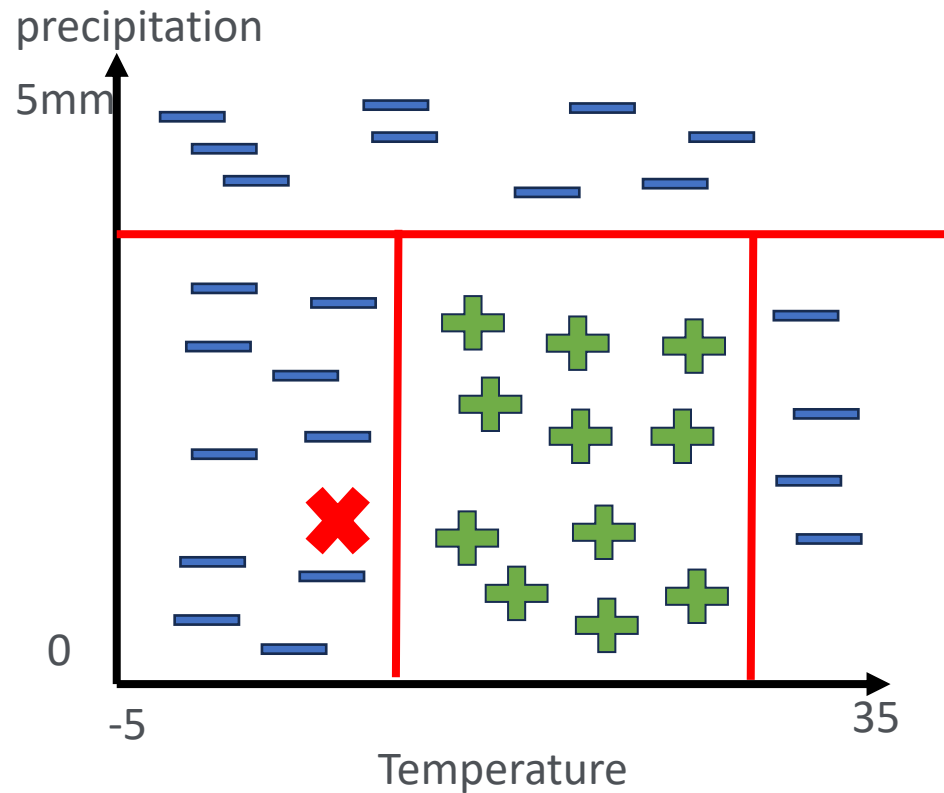
Build a decision tree

1. Divide the predictor space — that is, the set of possible values for X_1, X_2, \dots, X_p — into J distinct and non-overlapping regions, R_1, R_2, \dots, R_J .
2. For every observation that falls into the region R_j , we make the same prediction, which is simply the majority class of the outcome for the training observations in R_j .

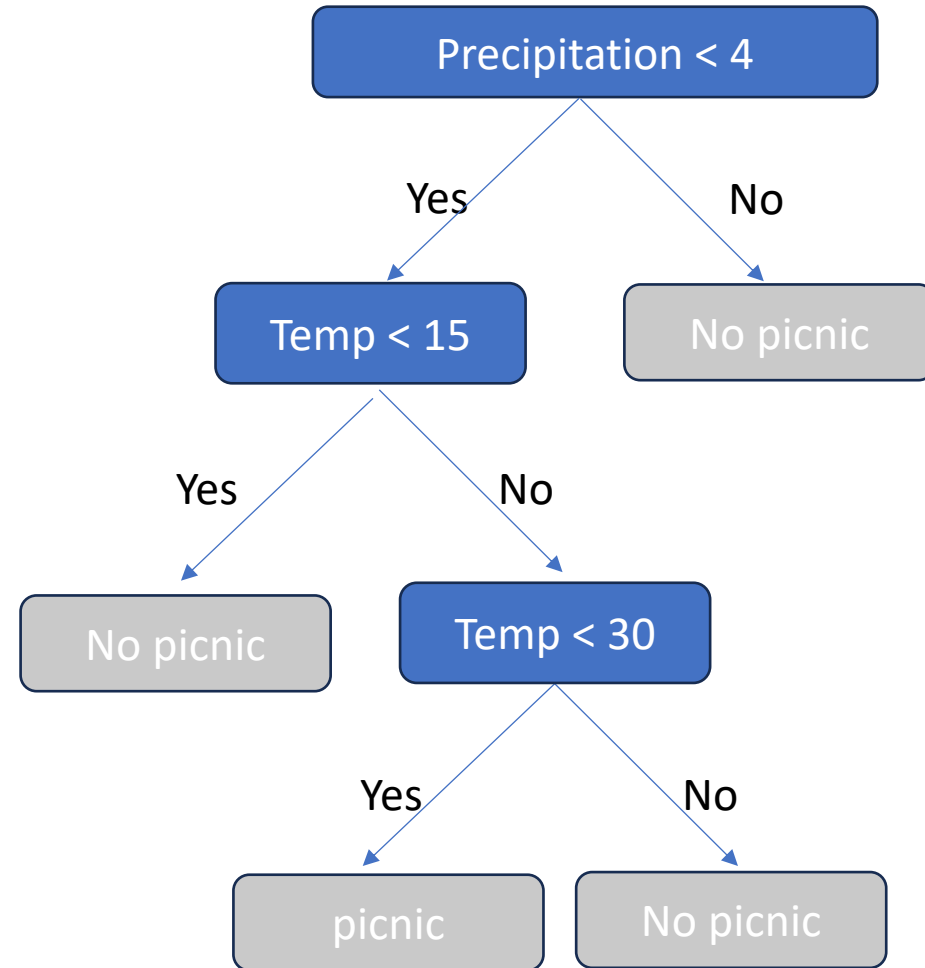


Basics of Decision Trees

- Shall we go to a picnic?

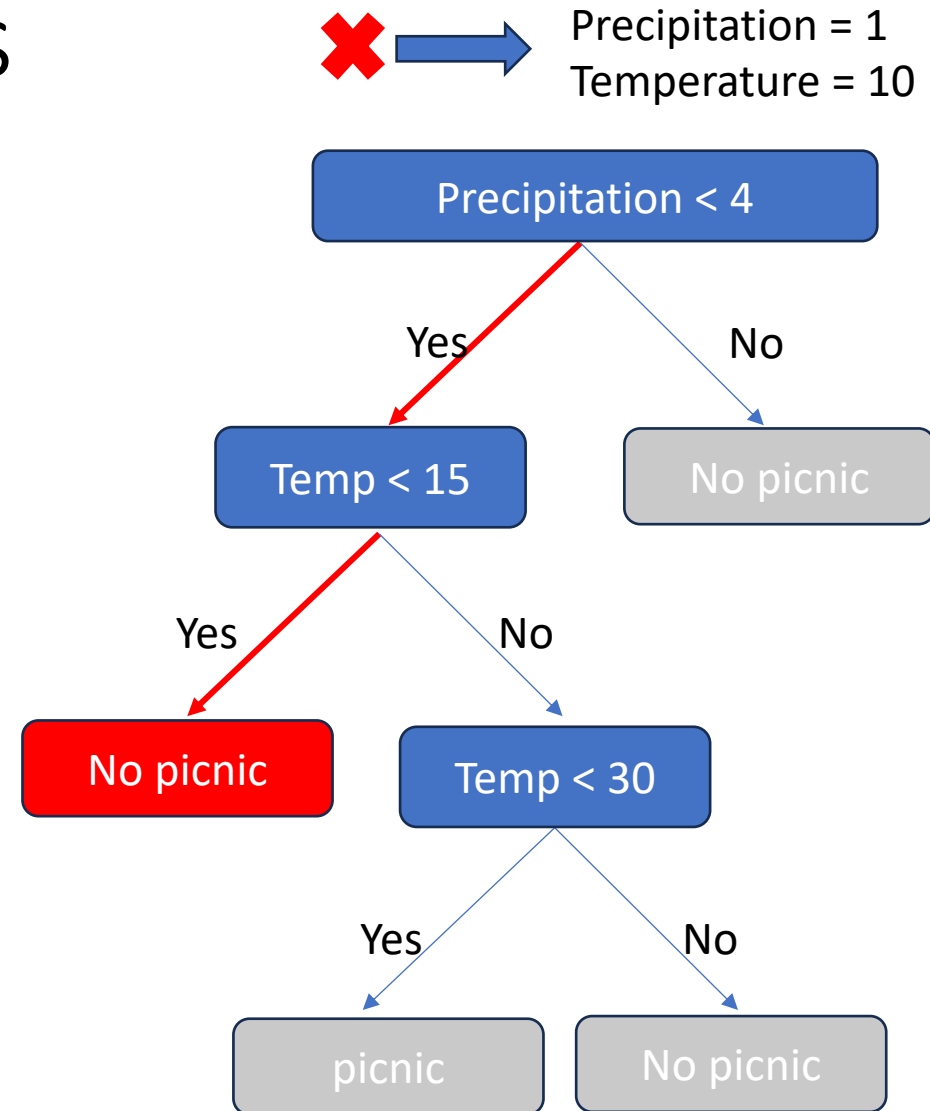
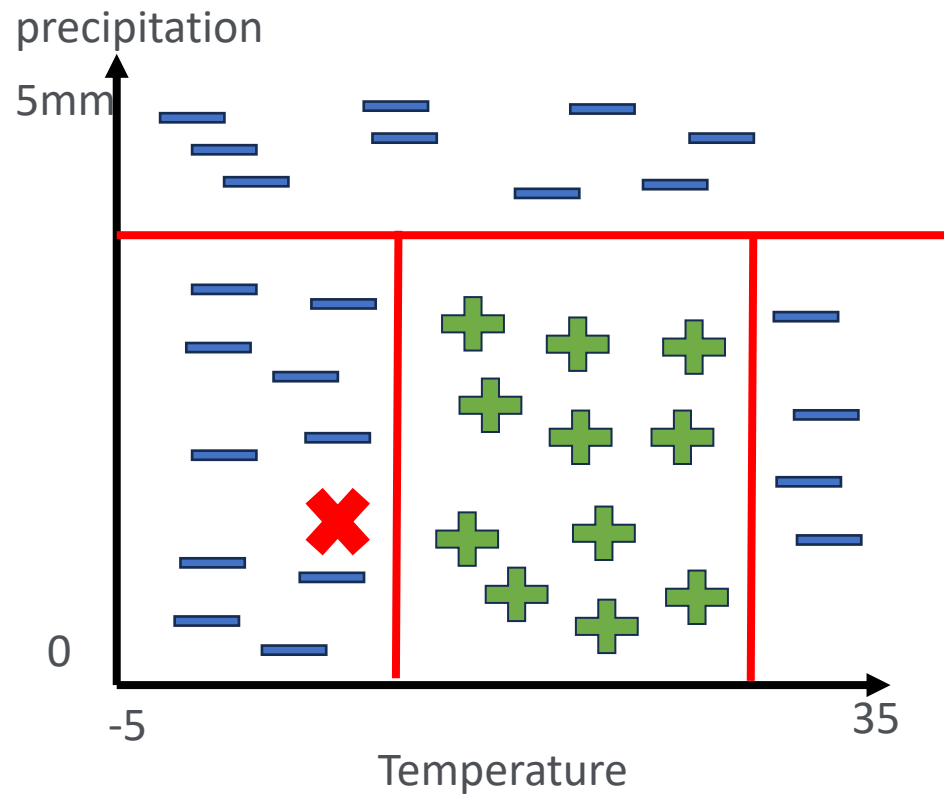


✘ → Precipitation = 1
Temperature = 10



Basics of Decision Trees

- Shall we go to a picnic?



Growing decision trees from data

- Recursive (binary) partitioning:
 1. Find the split that makes observations as similar as possible on the outcome within that split;
 2. Within each resulting group, do (1).
- Early stopping: add after (2):
- ‘unless there are fewer than n_{\min} observations in the group’ (typically 10)

Growing decision trees from data

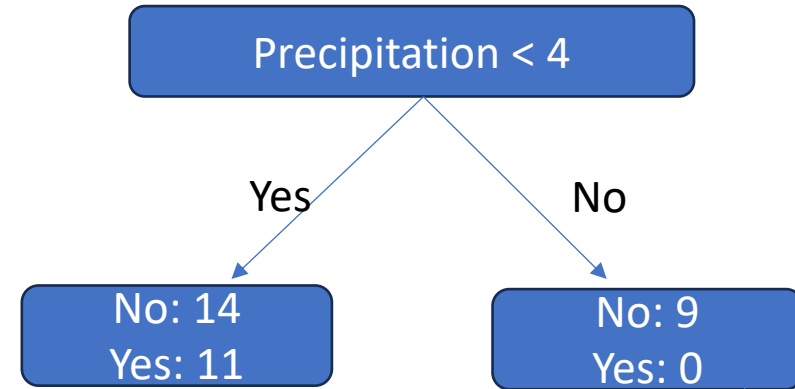
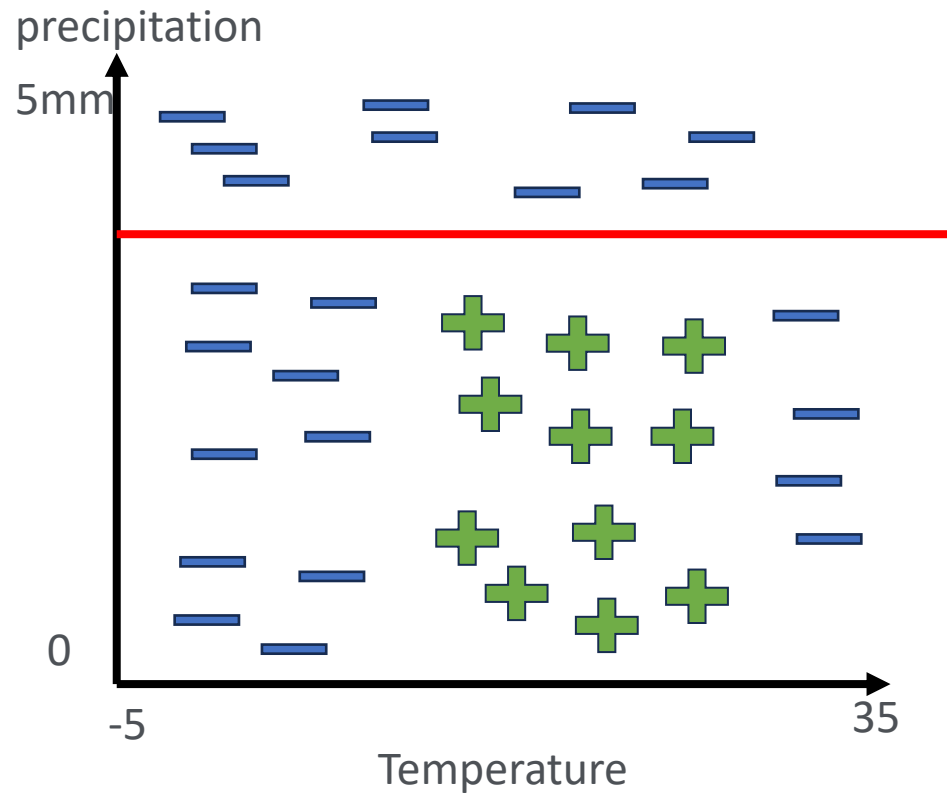
- Criteria for ‘as similar as possible’: reduction in classification error rate such as the **Gini impurity** or **entropy**

- Gini impurity:

$$G = \sum_{k=1}^K \hat{p}_{mk}(1 - \hat{p}_{mk}),$$

- \hat{p}_{mk} is the proportion of training observations in partition m with category k
- Small value: almost all values in the partition belong to one class
- Gini index is a measure of node *impurity*: small value indicates that a partition contains predominantly observations from a single class

Gini impurity



$$G = \sum_{k=1}^K \hat{p}_{mk}(1 - \hat{p}_{mk}),$$

For k = 0: $14/25 * (1-14/25) = 0.24$
 For k = 1: $11/25 * (1-11/25) = 0.24$

G = 0.49

For k = 0: $9/9 * (1-9/9) = 0$
 For k = 1: $0/9 * (1-0/9) = 0$

G = 0 + 0 = 0

Choosing Features

- Key Idea: good features partition the data into subsets that are either “all positive” or “all negative” (ideally)

Tree building: top-down and greedy

- Recursive (binary) partitioning is a top-down and greedy algorithm:
- **Top-down**: algorithm begins at the top of the tree and then successively splits the predictor space. Each split is indicated via two new branches further down on the tree.
- **Greedy**: at each step, the best split for that step is made, instead of looking ahead and picking a split that will result in the best tree in a future step.

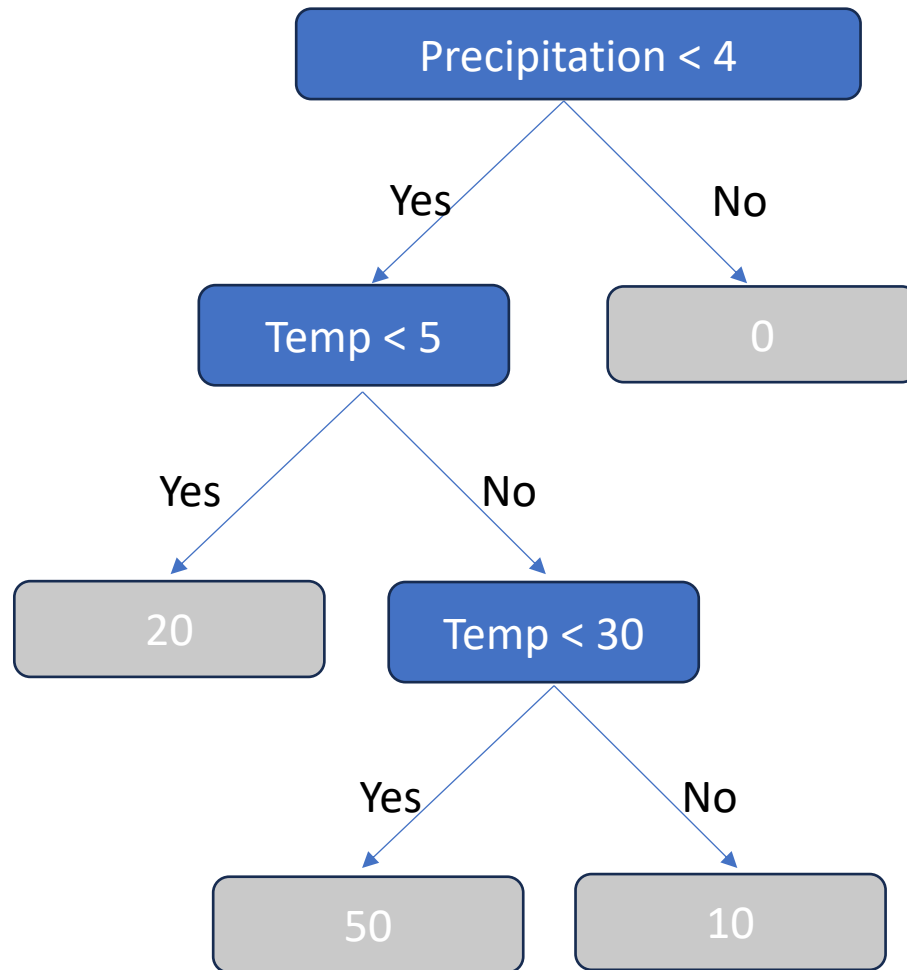


Regression Trees

Regression Trees

- Decision trees can be used for regression as well!
- Instead of predicting class label in each 'box' (partition), we predict the outcome in each partition:
 - mean of the training observations in the partition to which the test observation belongs
- Cutpoints are selected such that splitting the predictor space into the regions leads to the greatest possible reduction in residual sums of squares (RSS).
- CART: classification and regression trees

Regression Trees



Features:

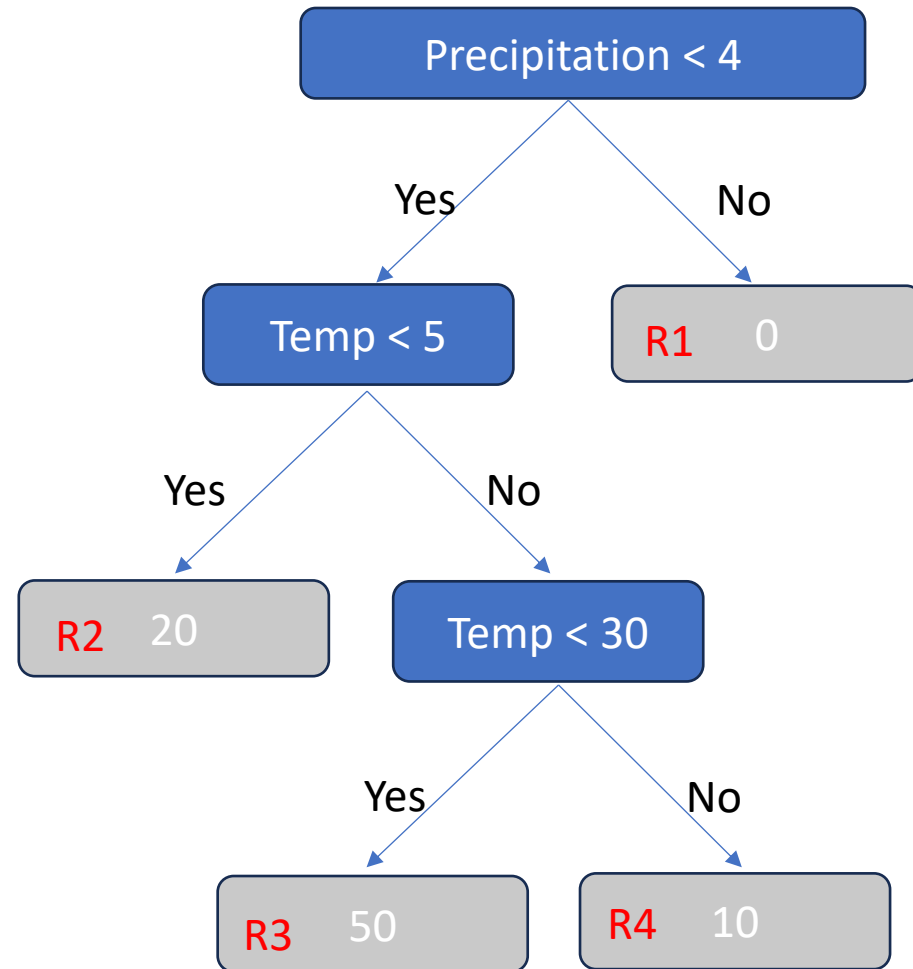
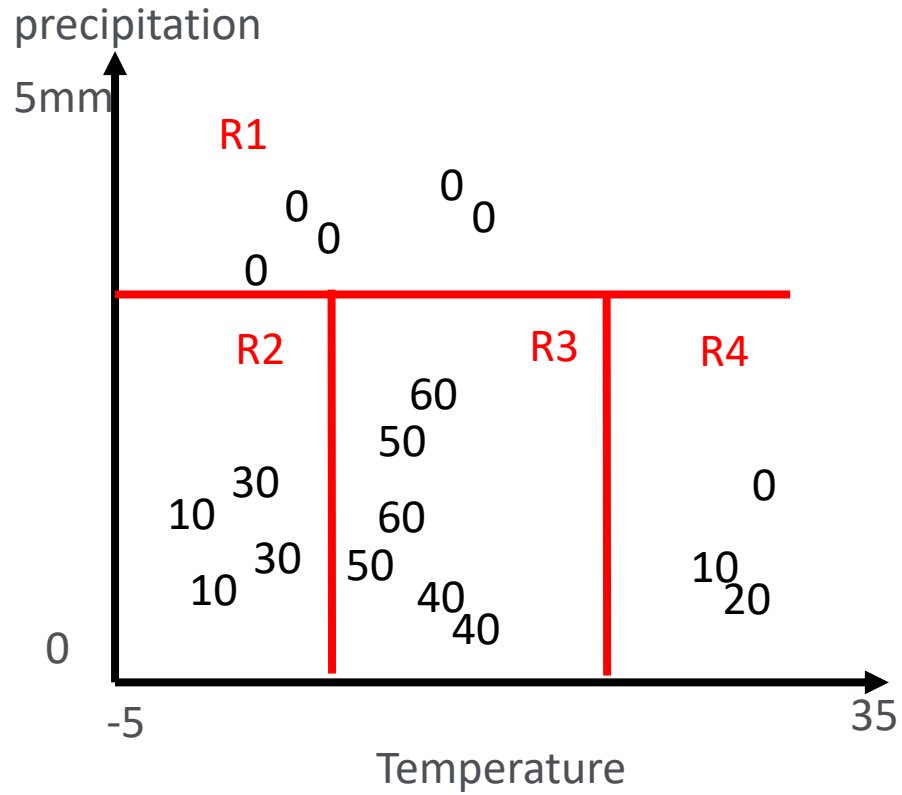
x1: precipitation

x2: temperature

y:

- minutes of outdoor training

Regression Trees



How to construct regions?

- The goal is to find boxes R_1, \dots, R_J that minimize the RSS

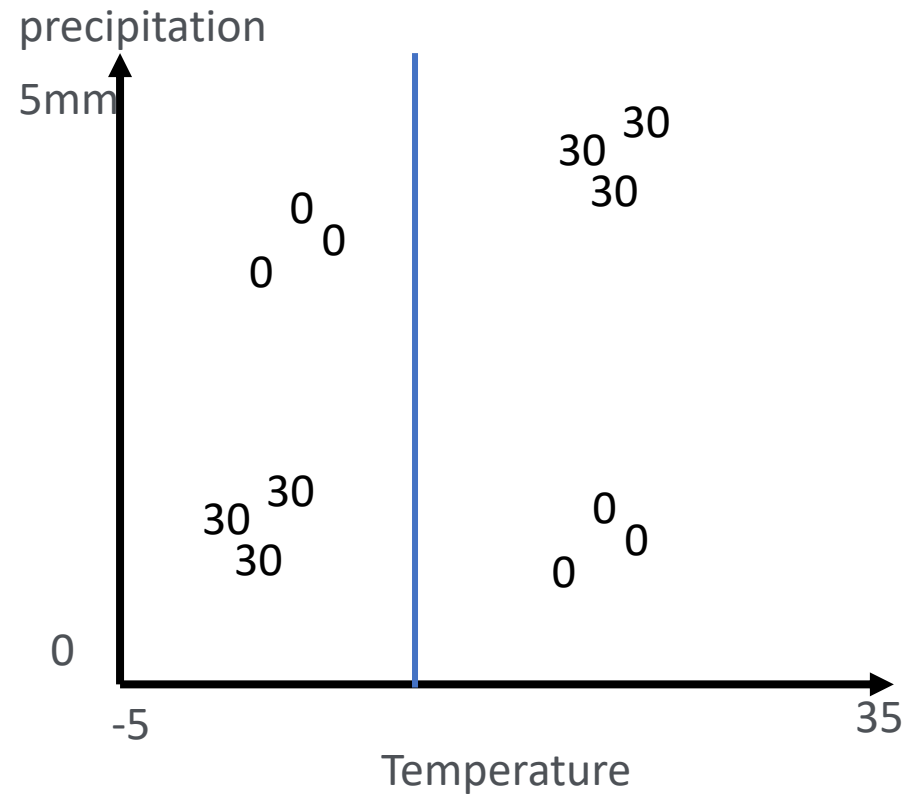
$$\sum_{j=1}^J \sum_{i \in R_j} (y_i - \hat{y}_{R_j})^2,$$

- Computationally infeasible to consider every possible partition of the feature space into J boxes

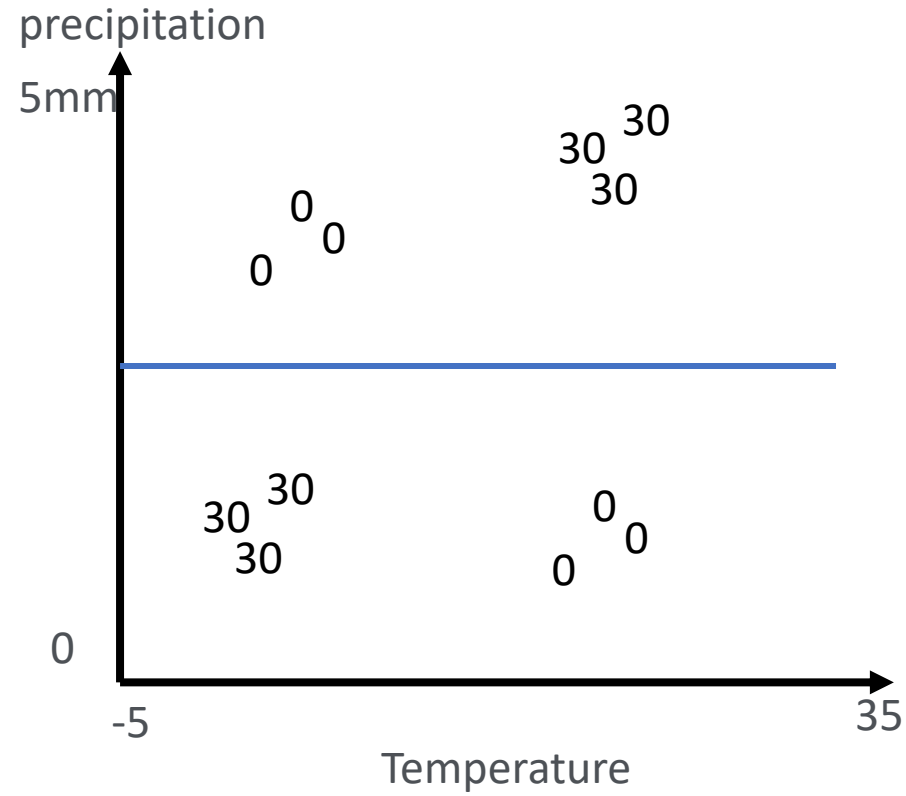
Pruning

- Process described to grow trees most likely overfits the data → poor test performance
- Solution 1: build the tree until the decrease in classification error / RSS exceeds some threshold
- This strategy will result in smaller trees
- However, a seemingly worthless split early on in the tree might be followed by a very good split

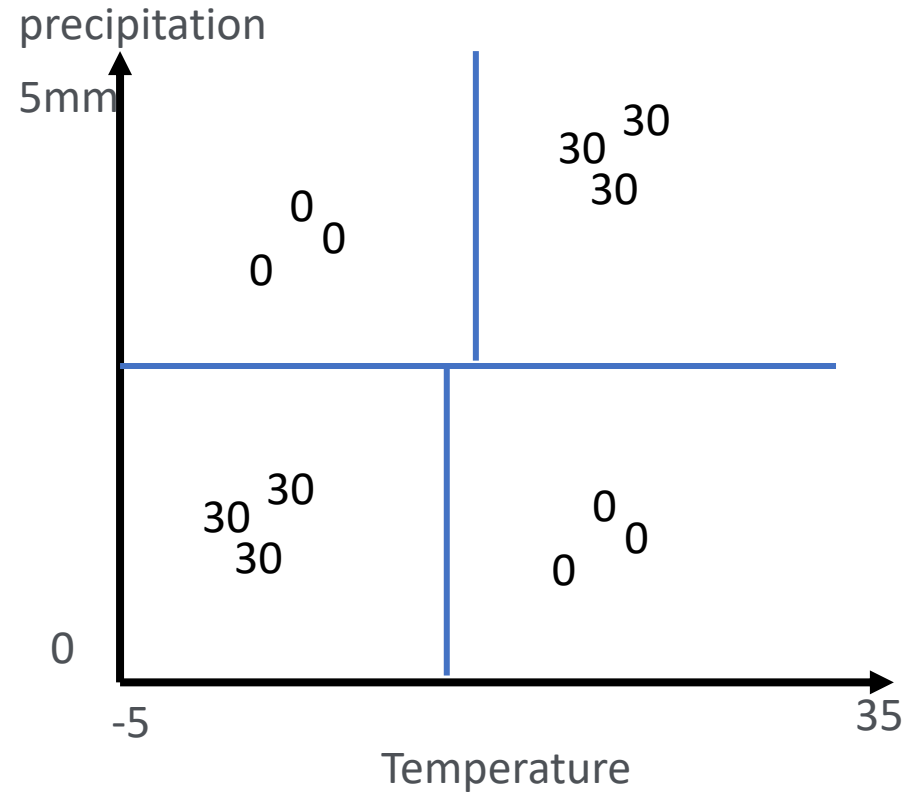
Pruning



Pruning



Pruning



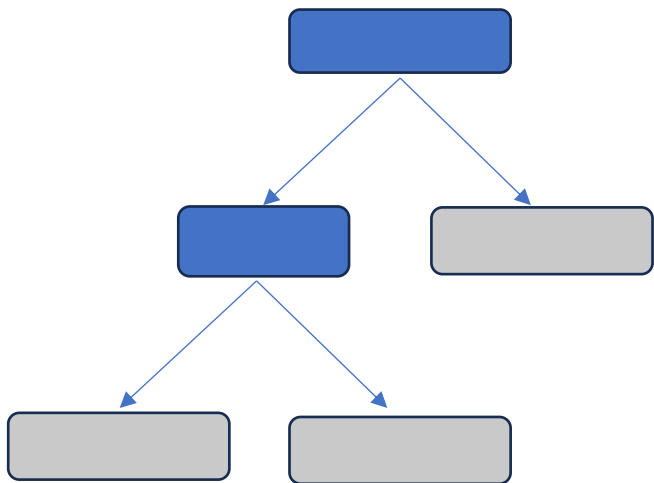
Cost Complexity Pruning

- Grow a large tree and then prune it back

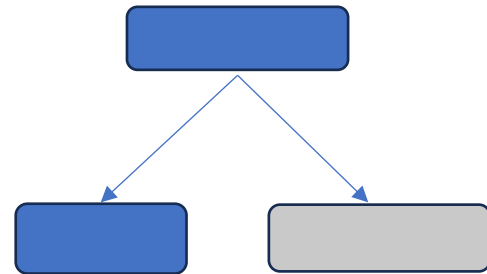
$$\sum_{m=1}^{|T|} \sum_{i: x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|$$

- $|T|$ is the number of terminal nodes
- R_m is the rectangle that corresponds to the m^{th} terminal node
- The tuning parameter α controls a trade-off between the subtree's complexity and its fit to the training data

$$\sum_{m=1}^{|T|} \sum_{i: x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|$$



Full tree
a = 0



Subtree 1
a = 10.000



Subtree 2
a = 15.000

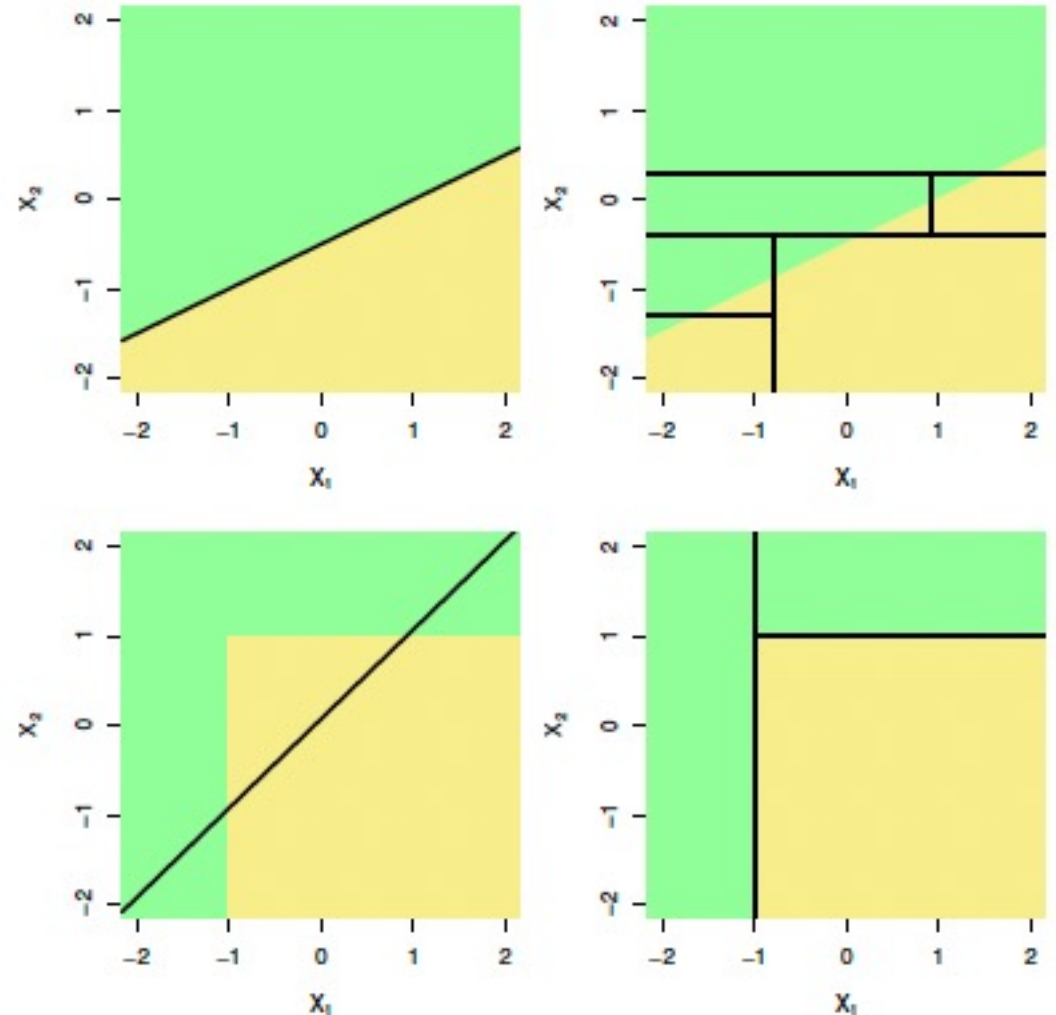
Cost Complexity Pruning

$$\sum_{m=1}^{|T|} \sum_{i: x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|$$

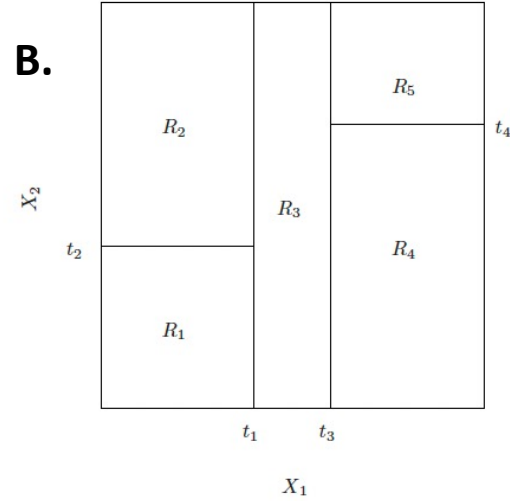
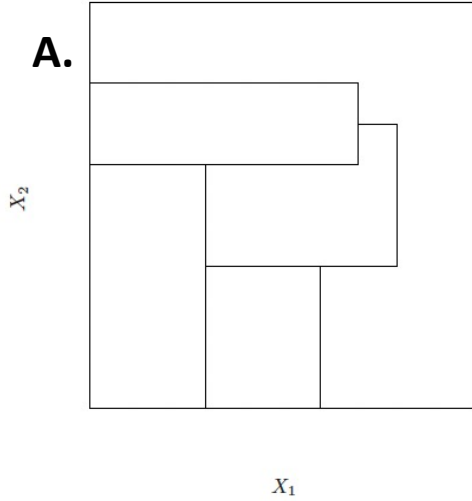
- $\alpha=0 \rightarrow$ subtree equals the original (long) tree
- As α increases, becomes more expensive to have a tree with many terminal nodes, resulting in a smaller subtree. Very similar to Lasso!
- Use K-fold cross-validation to choose α .

Linear Models VS Trees

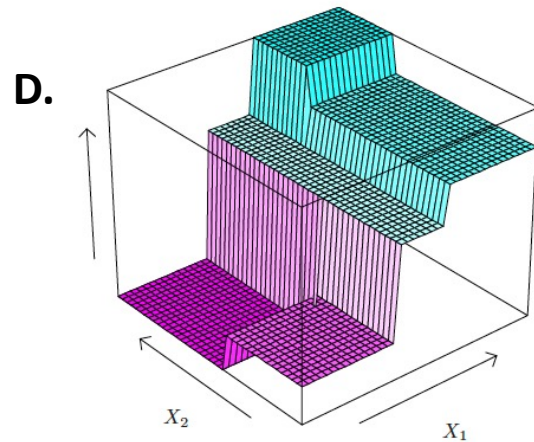
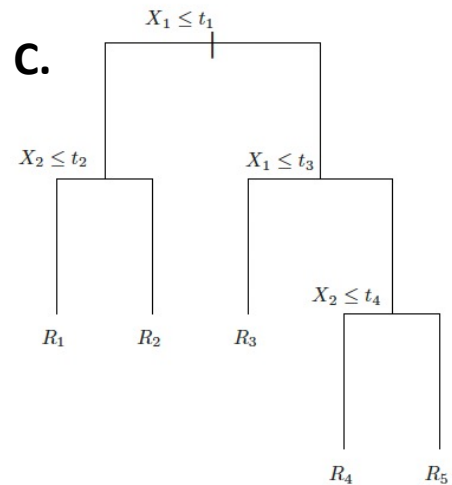
- Which model is better?
- It depends on the problem



Which of the panel(s) below cannot be representative of a decision tree model using recursive binary splitting?



[Copy participation link](#)



1

Go to wooclap.com

2

Enter the event code in the top banner

Event code
NYAIKH



Enable answers by SMS

Summary

- ✓ Trees are very easy to explain and interpret
- ✓ Mirror human decision-making better than other the regression and classification approaches
- ✓ Trees can be displayed graphically (sometimes)
- ✓ Detects non-linear relationships

Do not have the same level of predictive accuracy than other approaches

They are **prone to overfitting**: a small change in data can cause a large change in the final tree

Bagging and Random Forests



10 minutes break

A large, dark gray, curved shape that occupies the left side of the image, resembling a quarter of a circle or a large arc. It has a smooth, solid appearance.

Bagging

Intuition behind bagging

When you fiddle with the observations just a little:

1. Some things vary a lot;
2. Some things stay pretty much the same.

Intuition:

- Overfitting is caused by (1);
- but (1) happens randomly, causing predictions to go up or down haphazardly;
- Therefore, (1) should be cancelled out by fiddling with the observations a little and averaging
- “Wisdom of the crowds”

Bagging

- *Bootstrap aggregation*, or bagging (Breiman 1994):
- A general-purpose procedure for reducing the variance of statistical learning methods. It is very useful and often applied in the context of decision trees
- Averaging a set of independent observations reduces variance. But what if we only have one training set?

Bagging

- We can mimic having multiple training sets by bootstrapping:
- Generate B different bootstrapped training data sets.
- Train a decision tree on each of the b^{th} bootstrapped training set to get a prediction for each observation x : $\hat{f}^{*b}(x)$
- For regression trees, we average all predictions to obtain: $\hat{f}_{\text{bag}}(x) = \frac{1}{B} \sum_{b=1}^B \hat{f}^{*b}(x)$.
- For classification trees, we take the majority vote
- Do not need to prune: grow large trees in each bootstrapped sample, and variance is decreased by averaging

Training data

(X1, y1)
(X2, y2)
(X3, y3)
(X4, y4)
(X5, y5)

there are your rows, e.g., patient 1

e.g., patient 5

Training data

(X1, y1)
(X2, y2)
(X3, y3)
(X4, y4)
(X5, y5)

there are your rows, e.g., patient 1

e.g., patient 5

Bootstrap sample 1

(X1, y1)
(X2, y2)
(X5, y5)
(X4, y4)
(X5, y5)

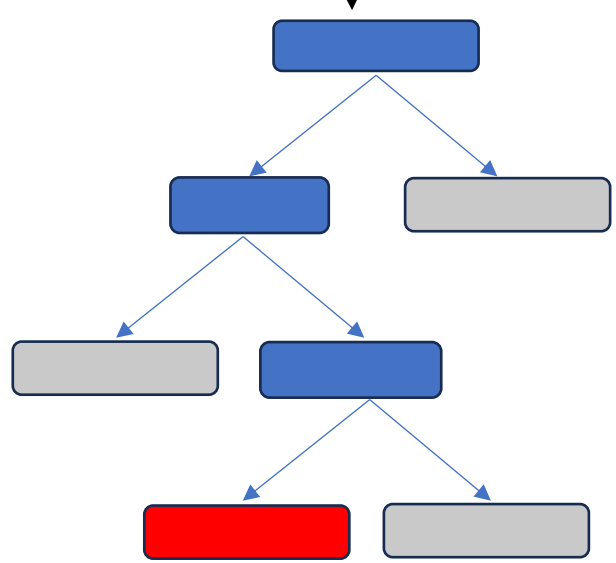
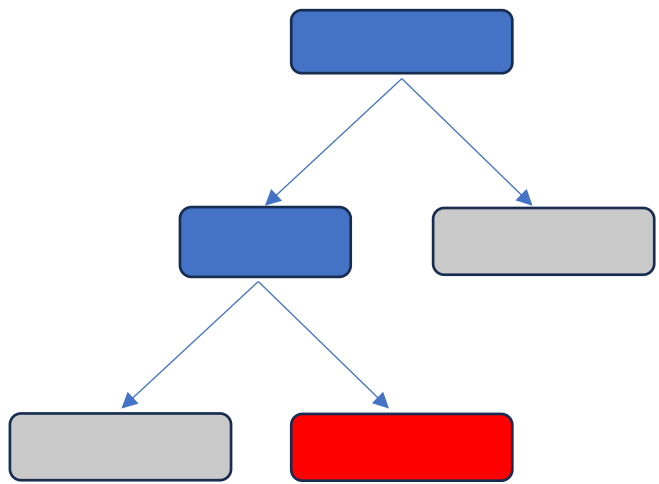
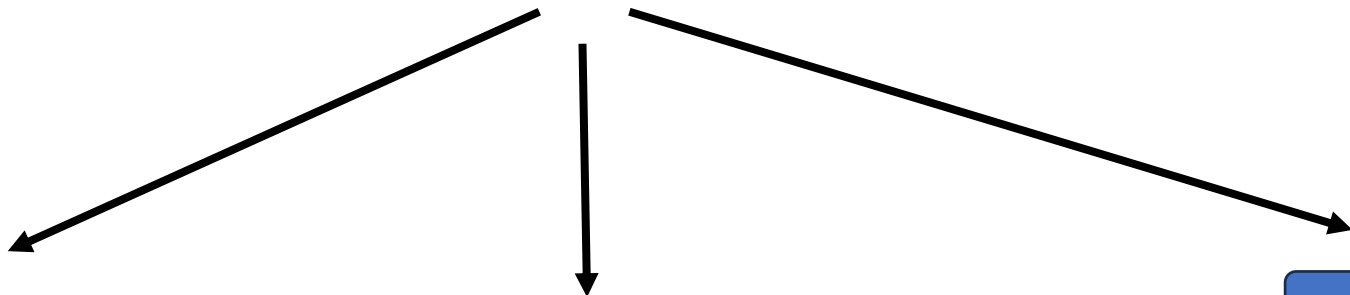
Bootstrap sample 2

(X2, y2)
(X1, y1)
(X3, y3)
(X1, y1)
(X2, y2)

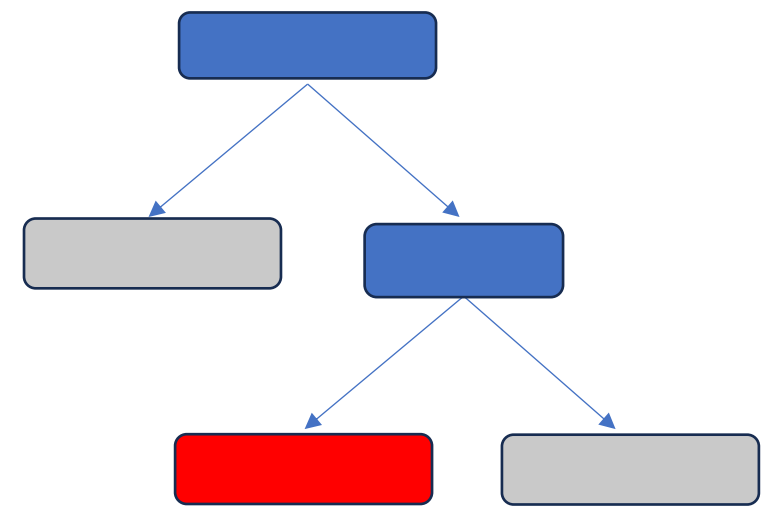
Bootstrap sample 3

(X4, y4)
(X2, y2)
(X3, y3)
(X4, y4)
(X1, y1)

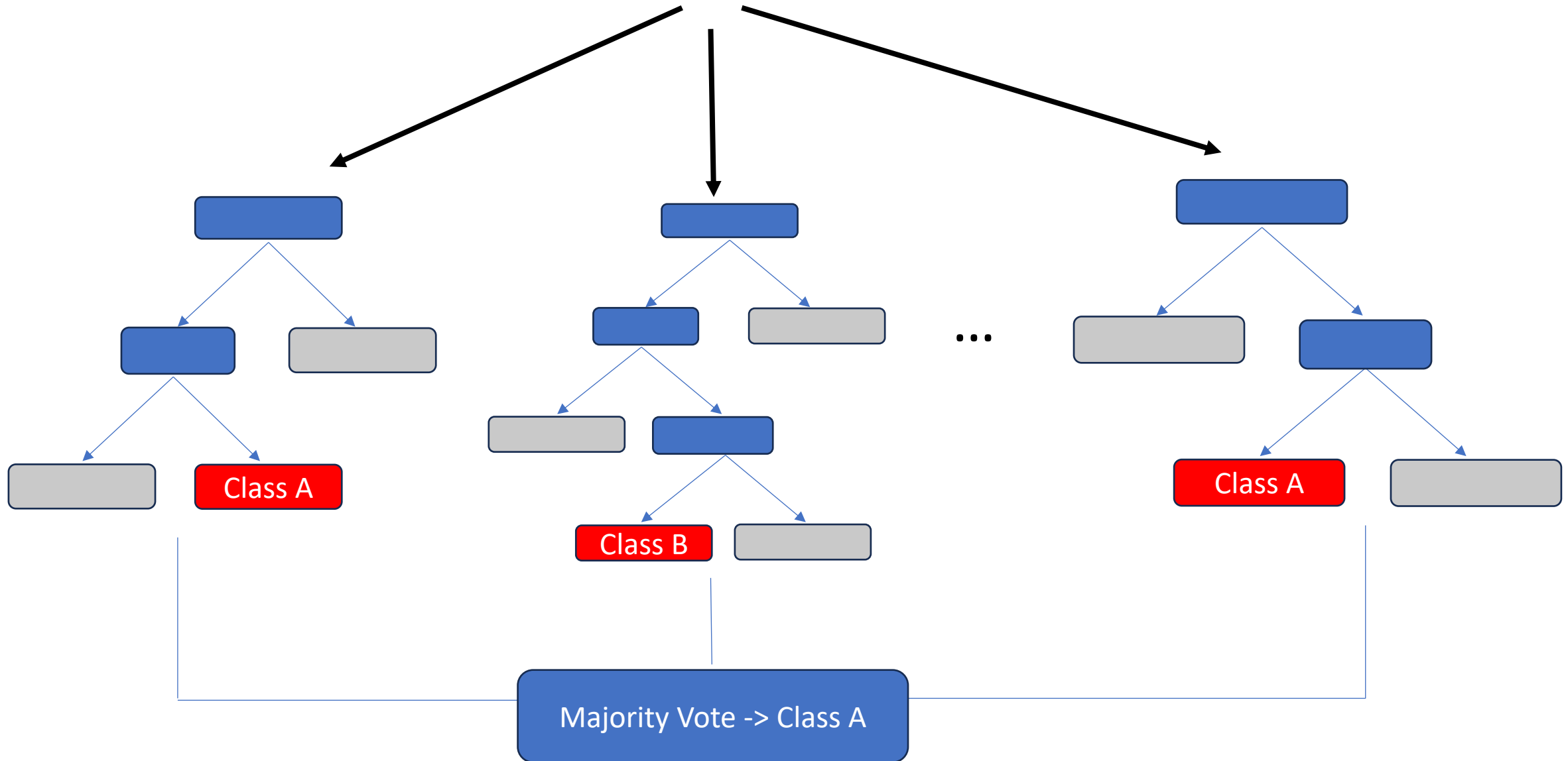
New test instance



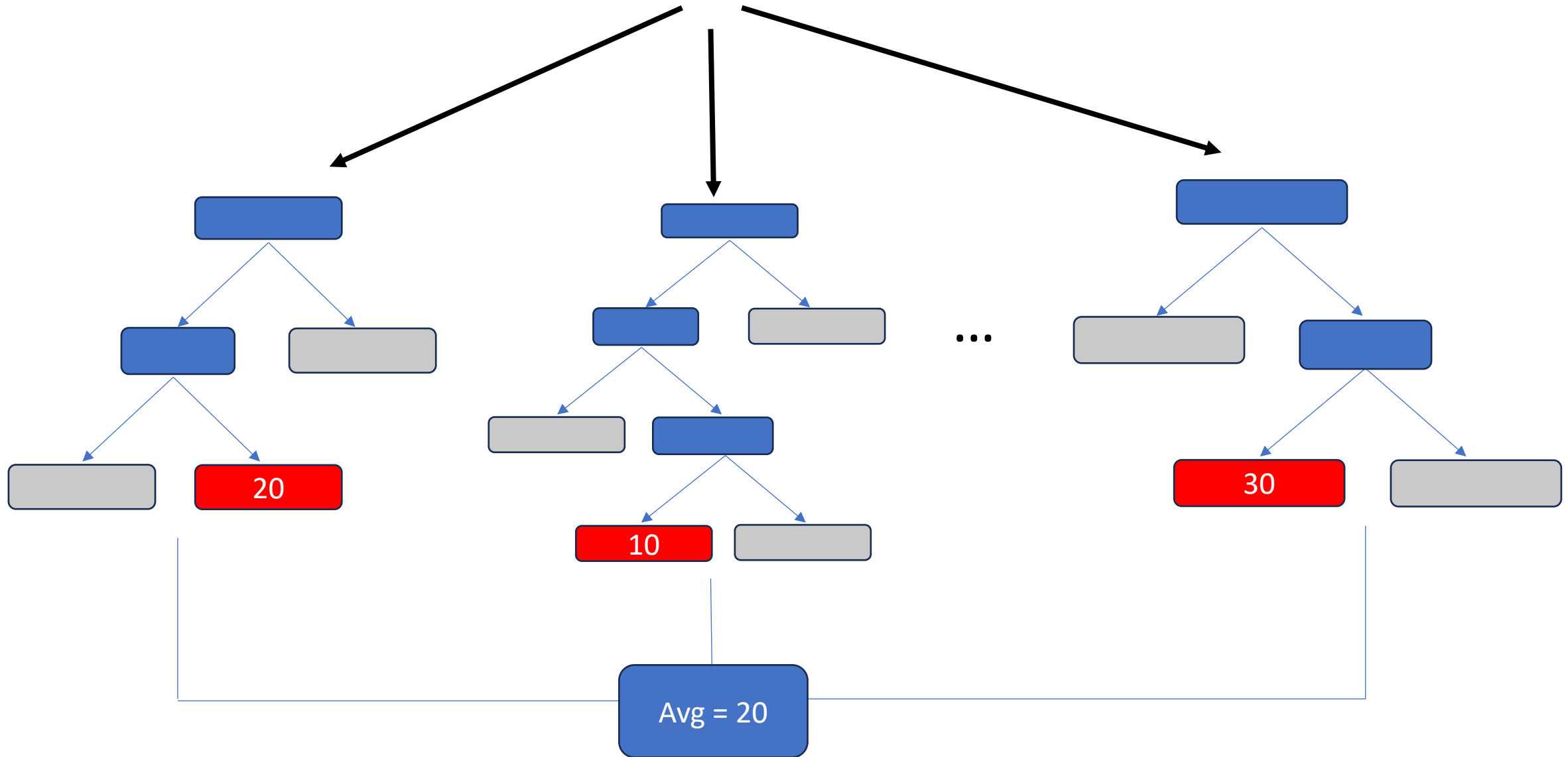
...



Classification: New test instance



Regression: New test instance





Random Forests

Random Forests

- In bootstrapping, the samples taken are independent.
- But the predictions from trees grown on the bootstrapped samples are not independent!
- They share the same features and can therefore create similarly overfitting decision rules
- “Wisdom of crowds who peek at each other’s answers”
- This phenomenon is called “tree correlation” (Breiman 2001)

Random Forests

- Random forests try to remove the tree correlation by feature sampling: randomly sampling both rows (bootstrapping) and columns

Random forest: feature sampling

- Decorrelation obtained by:
 - When building a tree, instead of using all variables when making a split, take a random selection of m predictors as candidates to base the split on
 - At each split, take a fresh selection of m predictors
- m is typically set to \sqrt{p}
- Similar to bagging, the collection of trees (= forest) is built on bootstrapped training samples
- Hence, bagging is a special case of a random forest with $m = p$.

Bootstrap sample 1

(X1, y1)
(X2, y2)
(X5, y5)
(X4, y4)
(X5, y5)



p1	p2	p3	p4	y

Bootstrap sample 1

(X1, y1)
(X2, y2)
(X5, y5)
(X4, y4)
(X5, y5)



p1	p2	p3	p4	y

1. Take one bootstrapped sample
2. Build a decision tree:
 - To find the best predictor, consider randomly 2 predictors to choose from

p3

e.g., To find the root of the tree consider only p2, p3

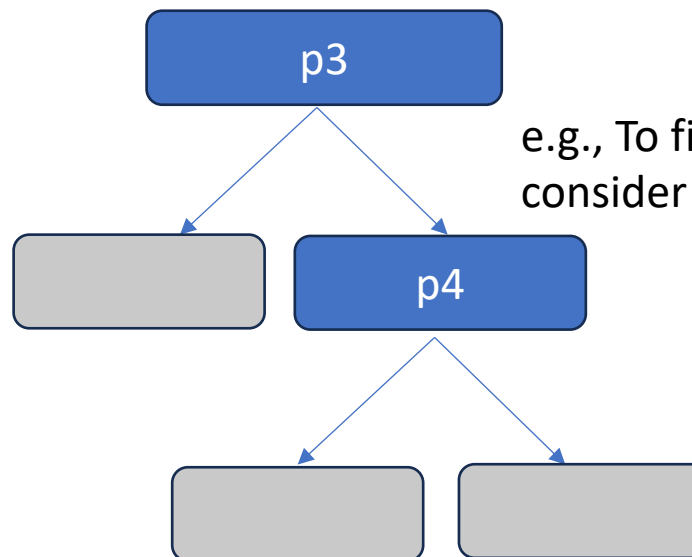
Bootstrap sample 1

(X1, y1)
(X2, y2)
(X5, y5)
(X4, y4)
(X5, y5)



p1	p2	p3	p4	y

1. Take one bootstrapped sample
2. Build a decision tree:
 - To find the best predictor, consider randomly 2 predictors to choose from

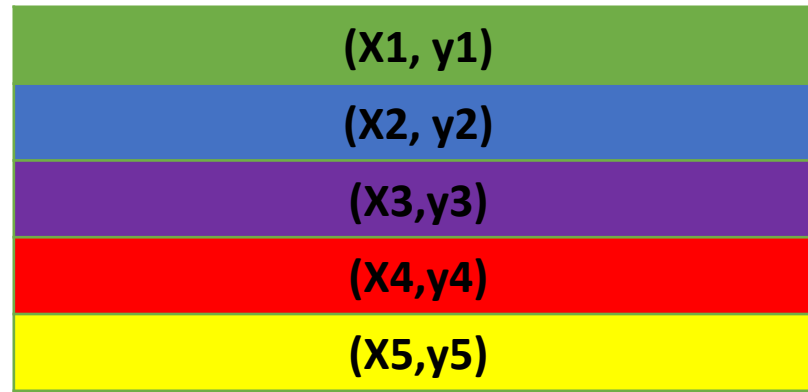


e.g., To find the predictor for the next split, consider only p1, p4

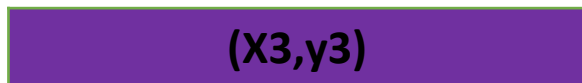
“Out-of-bag” error estimation

- When we do bagging and random forest, there is a very simple way to estimate the test error:
 - In both methods, we take multiple bootstrapped samples of the training data. On average, each tree uses about $2/3$ of the observations
 - The remaining $1/3$ of observations left out are referred to as the out-of-bag(OOB) observations
- If we want to calculate the error for a particular observation, we can predict the response using each of the trees in which it was OOB. This will give $B/3$ predictions for this observation, which we average. When we do this for all observations, we get the OOB error.
- Very close to leave-one-out cross-validation

Training data

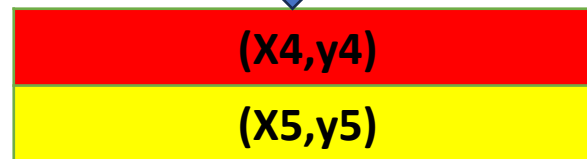
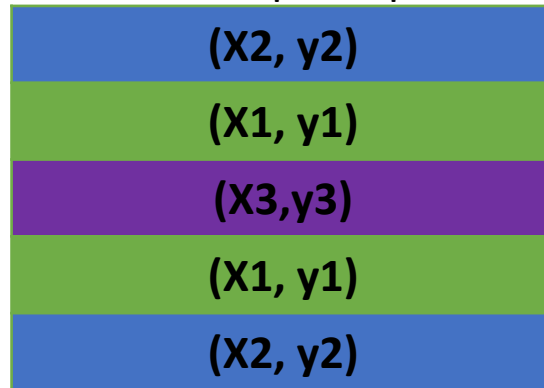


Bootstrap sample 1



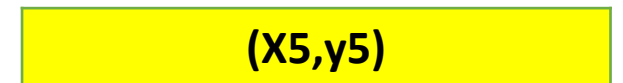
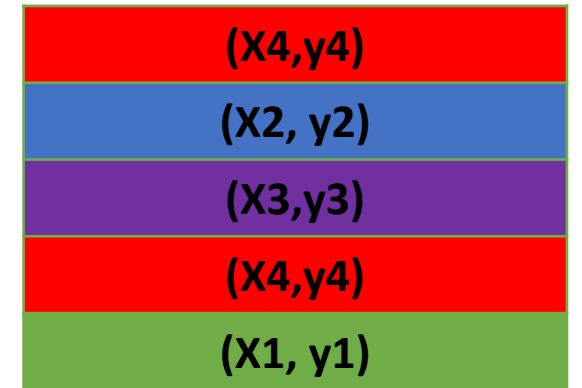
out of bag sample

Bootstrap sample 2

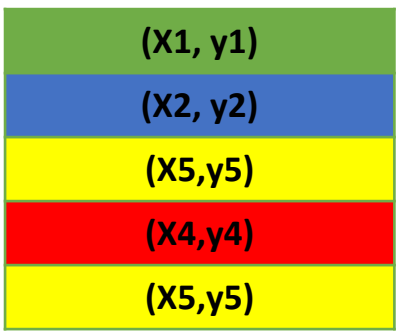


out of bag sample

Bootstrap sample 3



out of bag sample



out of bag sample



Class A

...



out of bag sample



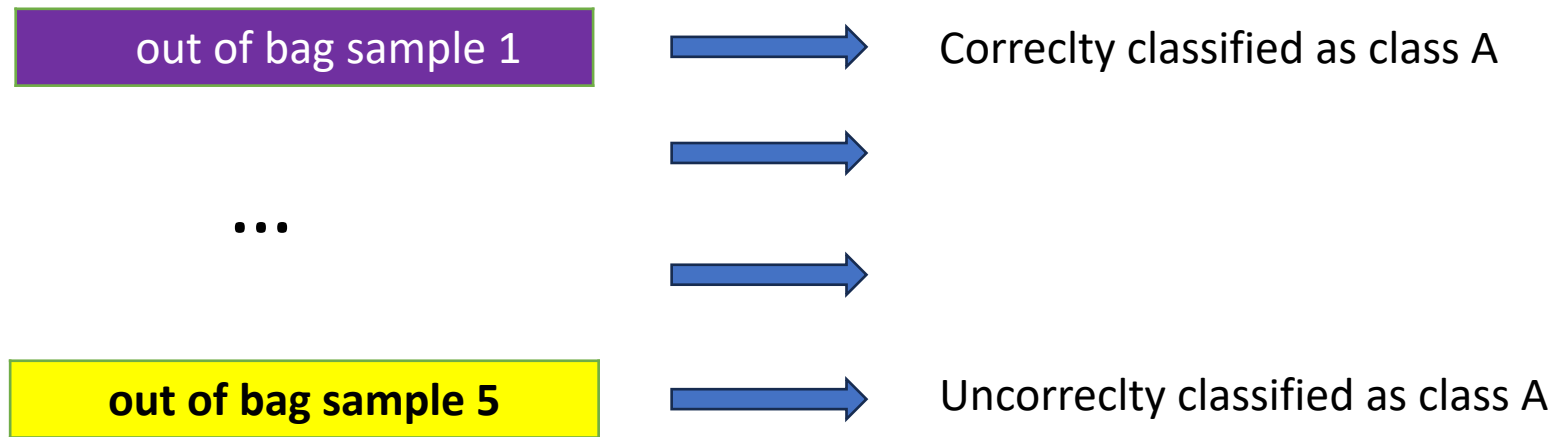
Class A

out of bag sample



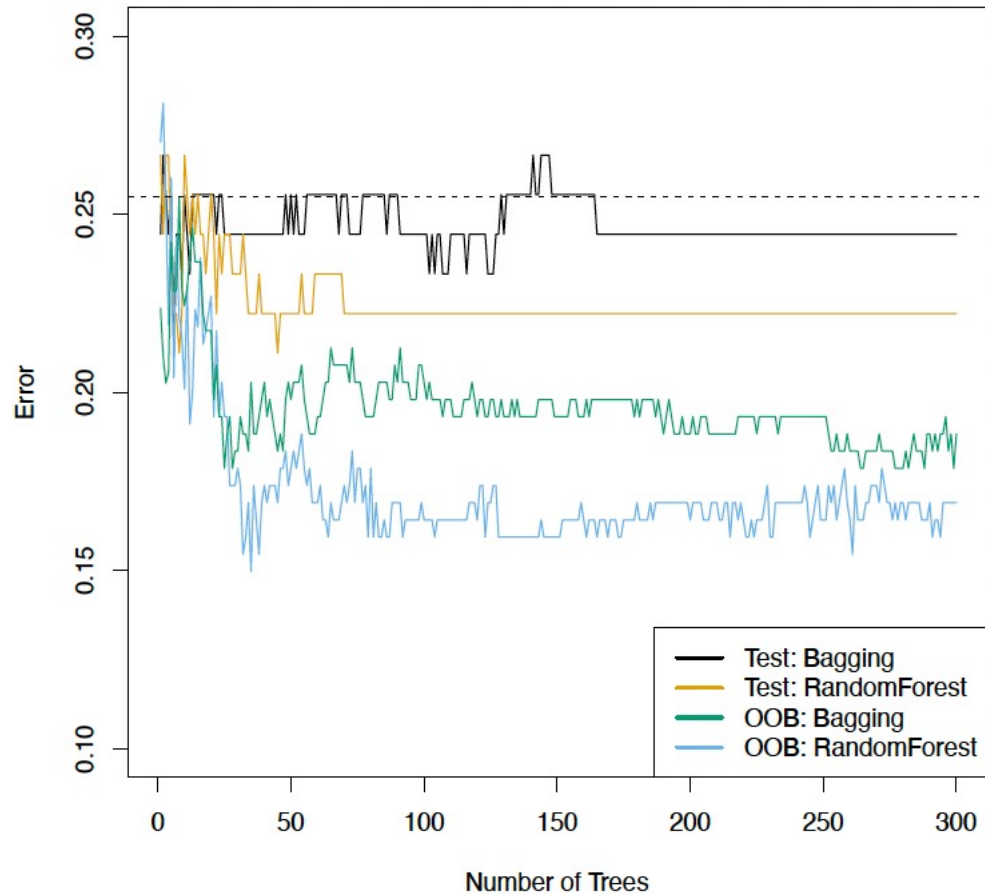
Correctly classified as class A

“Out-of-bag” error



- We can measure how accurate our random forest is by the proportion of out-of-the-bag samples that were correctly classified
- The proportion that was incorrectly classified is the Out-Of-Bag error

bagging vs random forest



- The dashed line indicates the test error resulting from a single classification tree.
- The test error (black and orange) is shown as a function of B , the number of bootstrapped training sets used.
- The green and blue traces show the OOB error, which in this case is — by chance — considerably lower.

Variable importance measure

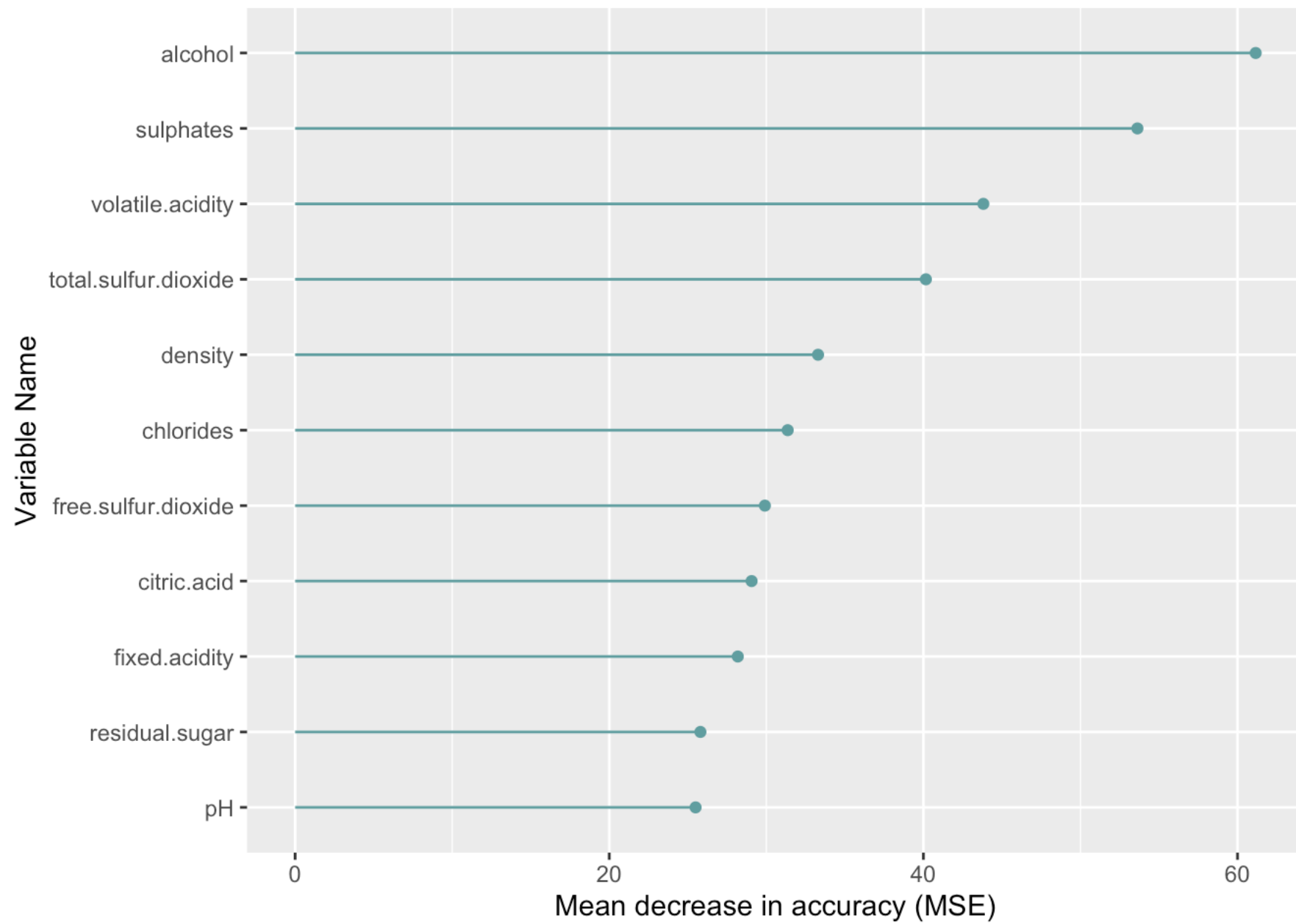
- In both bagging and random forest, it can be difficult to interpret the resulting model:
 - When we build a large number of trees, it is no longer possible to (graphically) represent the resulting statistical learning procedure using a single tree
 - How to find out which predictor(s) are most important in predicting a correct outcome?
- Variable importance measures
- Larger value indicates a more important predictor

Impurity-based feature importance (MDI)

- How “important” is variable x_j to the prediction?
- Recall that trees (classification or regression) are grown by minimizing “impurity” (e.g. Gini)
- IDEA: Record the total amount that impurity is decreased due to splits over x_j , averaged over all B trees (MDI)
- Advantage:
 - Obtained for free with estimation
- Disadvantages:
 - importance of features used to overfit inflated
 - importance of numerical features inflated

Permutation-based feature importance

- IDEA: randomly shuffle one column, and observe how much worse it makes the model
- Advantage: Doesn't have the problems of MDI
- Disadvantages:
 - Can take a while, results vary
 - Ignores correlations among predictors (e.g. perfectly correlated features are all “unimportant”)



Quiz time!



- 1 Go to wooclap.com
- 2 Enter the event code in the top banner

Event code
NYAIKH

 Enable answers by SMS

 [Copy participation link](#)

Summary

- Decision trees are simple and useful for interpretation
- However, prone to overfitting. Solutions: pruning, bagging and random forests
- Bagging: fit multiple trees to bootstrapped samples of the data, combine to yield a single consensus prediction
- Random Forest: fit trees to bootstrapped samples from the data AND sample predictors. Combine all trees to yield a consensus prediction

Summary

- When using bagging and random forests we can approximate the test error using the Out of Bag (OOB) estimate of the error
- Which predictor is most influential on the outcome can be inferred from variable importance measures
- Random forests often show top-tier performance out of the box, but the resulting model is difficult to interpret

Practical on Thursday.

Preparation: make sure to have finished the homework section

Next week: Introduction to text mining (**ONLINE**)

Link for the MS teams on BB; join before Sunday 😊

Have a nice day!